1	ELECTRIC MOTOR WITH NONMOTOR	568.13	With particular program
1	DRIVING MEANS (E.G., AXLE		teaching method
	DRIVING MEANS (E.G., AADE DRIVE, MANUAL DRIVE)	568.14	Manual lead through
2	.Manual driving means	568.15	With particular interpolation
3	WITH PARTICULAR MOTOR-DRIVEN LOAD		means
3	DEVICE	568.16	With particular sensing
4	.Plural, diverse or diversely		device
-	controlled load device	568.17	With multimode control (e.g.,
5	Plural motor drive		course-fine, position-force,
6	.Tension-maintaining type of		etc.)
	motor-control system	568.18	Including velocity control
7	Plural, diverse or diversely	568.19	With particular coordinate
	controlled motors		transformation means
8	.Plural, diverse or diversely	568.2	With plural control systems
	controlled driving motors		(e.g., the interaction of
	(e.g., driving differential		plural processors to control
	gearing)		the plural joints of a single
9	.Power- or motion-transmitting	F.CO. 01	robot):
	mechanism	568.21	Including end effector
10	Reversible drive mechanism		(e.g., gripping jaw,
11	Variable speed mechanism	568.22	micromanipulator, etc.)
12	Gearing	300.22	With particular compensation (e.g., gain, offset, etc.)
13	Differential type	568.23	Including program
14	Motion-converting mechanism	500.∠5	modification
15	Mechanical gearing	568.24	With reliability enhancement
16	SUPPLIED OR CONTROLLED BY SPACE-	300.24	means (e.g., monitoring,
	TRANSMITTED ELECTROMAGNETIC OR		redundant circuits, etc.)
	ELECTROSTATIC ENERGY (E.G., BY	568.25	Including display device
1 7	RADIO)	569	Digital or numerical systems
17	PORTABLE-MOUNTED MOTOR AND/OR PORTABLE-MOUNTED ELECTRICAL	570	Contouring systems
	SYSTEMS THEREFOR	571	With "feed-rate" control
560	POSITIONAL SERVO SYSTEMS (E.G.,	572	With "zero-offset" or tool
300	SERVOMECHANISMS)		radius correction
561	.Adaptive or optimizing systems	573	With interpolating means
001	including "bang-bang" servos	574	Multiple axes point to point
562	.Time-sharing or multiplexing		systems
	systems	575	Multiple axes analog systems
563	.With protective or reliability	576	Nonmechanical line, seam or
	increasing features (e.g.,		edge followers
	"fail-safe" systems)	577	Optical or photoelectric line
564	"Redundant" operating channels		followers
565	Monitoring systems	578	Cam or template followers
566	Maneuver, force, or load-	579	Multiple pass systems
	limiting	580	.Vehicular guidance systems with
567	.Program- or pattern-controlled	E 0.4	single axis control
	systems	581	Radio-controlled
568.1	With program recording or	582	Celestial navigation
	composing means	583	Landing systems
568.11	Multifunction manipulator	584	Altitude or pitch control
	(i.e., Robot)	585	Roll control
568.12	Mobile robot	586	Yaw control
		587	Land vehicles

588	Marine vehicles	625	.Plural servomotors
589	Submarine and torpedo systems	626	.Limit or end-stop control
590	Submarine and torpedo systems .Multiple mode systems	627	Secto-scanning systems
591	With mode-engagement features	628	."Feelback" systems
J J I	(e.g., manual to automatic)	629	. reelback systems .Unwanted harmonic or voltage
592	Fine and coarse systems	029	component elimination
593	Separate fine and coarse		quadrature rejection systems
333	motors	630	.Antibacklash systems (e.g., with
594		050	unidirectional approach to
595	Digital systemsMultiple speed synchro systems		balance)
596	Combined "on-off" and	631	.Antistatic friction features
390	proportional control	031	(e.g., "dither" voltage)
597	Slewing systems	632	.With compensating features
598	With a separate slewing motor	633	"Two-cycle error" compensation
599	with a separate slewing motor .Pulse-width modulated power	634	Temperature compensation
333	input to motor (e.g., "duty	635	.With signal-, voltage-, or
	cycle" systems)	033	current-limiting
600	.Digital or numerical systems	636	."Sampling" systems including
601	Digital comparison	030	miscellaneous "sampled data"
602	Commutating switch-type		control systems
002	encoder	637	.Analog computation
603	Pulse-counting systems	638	.With particular "error-
604	Analogue comparison		detecting" means
605	Synchro or resolver (e.g.,	639	Plural, diverse conditions
003	transmitter simulators)	640	Photoelectric or optical-type
606	.Frequency- or phase-modulated		measuring instruments
000	systems	641	With particular temperature
607	Frequency comparison		measuring instrument
608	Phase comparison	642	With liquid level measuring
609	."Reset" systems (P.I.)		instruments
610	With rate (P. I. D.) (e.g.,	643	With moisture content or
	reset windup prevention)		wetness measuring instruments
611	.With stabilizing features (e.g.,	644	With flow measuring instruments
	anti-hunting, damping)	645	With fluid pressure measuring
612	Electric braking near balance		instruments
	(e.g., dynamic)	646	With force or weight measuring
613	D.C. in A.C. windings		instruments
614	Friction-braking near balance	647	With magnetic field measuring
	including magnetic or eddy		instruments
	current brakes	648	With inertial, direction or
615	By auxiliary feedback loop		inclination measuring
616	Rate feedback		instrument
617	Variable rate feedback	649	Stable platforms
618	Tachometer feedback	650	With current, voltage or
619	Variable gain bandwidth		electrical power measuring
620	Nonlinear circuits		instruments
621	Lead or lag networks	651	With acceleration measuring
622	A.C. networks		instruments
623	Load stabilization (e.g.,	652	With particular position
	viscous, magnetic or friction	650	measuring instruments
	dampers)	653	Magnetic transducers
624	By deadband at null (e.g.,	654	Synchro control transmitter-
	threshold circuits)	655	transformer systems
		655	With synchro differential

656	Differential transformer systems	692	.Having induction or "selsyn" type transmitter
657	Linear differential	693	.Having impedance-type
	transformer		transmitter
658	"E" type transformer	694	.Having commutated dynamoelectric
659	"Microsyn" type		machine transmitter
660	"Inductosyn" systems	695	.Having commutating switch-type
661	Resolver systems		transmitter
662	Variable capacitor systems	696	OPEN-LOOP STEPPING MOTOR CONTROL
663	Potentiometer systems		SYSTEMS
	including autotransformers and	34	PLURAL, DIVERSE OR DIVERSELY
	Wheatstone bridges		CONTROLLED ELECTRIC MOTORS
664	Minor arc seeking	35	.Motors with diverse motions
665	Continuous rotation,		(e.g., reciprocating and
	unlimited range		rotary motors)
666	Controlled tap and slidewire	37	.Plural reciprocating or
667	With a bridge in the feedback		oscillating motors
	circuit	38	.Plural linear-movement motors
668	Recalibrating systems	39	.Work and feed motors (e.g.,
669	Standing wave		indexing)
670	Contact resistance	40	.Motor biased against rotation
671	.With particular motor control	41	.Having electrical synchronizing
	system responsive to the		interconnections
	"actuating signal"	42	Between windings on auxiliary
672	Discontinuous or "on-off"	4.0	dynamo-electric machines
	control	43	D.C. or A.C. commutator motors
673	Seeking switch type		with slip rings
674	Wheatstone bridge type	44	Between induction motor
675	One transmitter or controller	4.5	secondaries
	element follows another	45	.Mechanically coupled in fixed
676	Transmitter or controller	1.0	ratio of movement
	<pre>element returned (e.g., force balance systems)</pre>	46	Motors having unlike operating characteristics
677	With particular servoamplifier	47	Synchronous and nonsynchronous
678	Differential amplifier		motors
679	Diverse types of amplifiers in	48	Mechanically coupled in torque
	different stage		opposition
680	Magnetic servoamplifiers	49	.Motors electrically connected in
681	Solid-state servoamplifiers		cascade or tandem
682	Rotating amplifier (e.g.,	50	With means for effecting other
	"Ward Leonard" control)		motor interconnections
683	With particular phase	51	.Plural, diverse motor controls
	discriminator		for different motors
684	With particular modulator or	52	.Slipping and/or racing control
	<pre>detector (e.g., choppers)</pre>		for electric motors
685	"Step-by-step" motors in	53	.Plural, diverse motor controls
	closed-loop servos	54	Motor-reversing
686	Reciprocating or oscillating	55	With running-speed control
	motors	56	And braking
687	Linear movement motors	57	And braking
688	Shaded pole motors	58	And acceleration control
689	TORQUING MOTORS	59	Running-speed control
690	SELF-SYNCHRONOUS TYPE OF MOTOR	60	And braking
691	.With means to amplify	61	And acceleration control
	transmitter signals		

progressing or traveling motor

.Plural, diverse or diversely

controlled motor windings

field flux

122

90

91

motor

.Acceleration control

..Accelerating motors in

succession or selectively

123	Polyphase or diverse or	149	.With plural, diverse or
	diversely controlled sources		diversely controlled
	of motor supply		generators
124	A.C. and D.C. sources	150	.With flywheel on generator or on
125	Unidirectionally conductive		motor
125	-	151	.Control of both the generator
106	devices in energizing circuit	131	3
126	.Energizing winding circuit		and the circuit to the motor
	control	152	With motor control
127	Automatic in response to	153	.Control of both the generator
	predetermined position,		and the motor
	movement or condition in or of	154	Control of excitation (field)
	the motor or driven device		circuit of both
128	Noise, sound, vibration,	156	.Plural, diverse or diversely
	movement or position of motor		actuated, generator control
129	By means for producing periodic		means
127	electrical pulses in the	157	
		_	.Generator speed control
120	energizing circuit	158	.Generator field circuit control
130	Electrical oscillation or	159	HAVING ROTOR ELEMENT BIASED
	condenser charging and/or		AGAINST ROTATION
	discharging circuits	160	.By resilient biasing means
131	Motor or escapement-controlled		(e.g., spring)
	means	161	WITH FLYWHEEL OR MASSIVE ROTARY
132	By space-discharge or		MEMBER
	unidirectionally conductive	162	CONTROL BY PATTERNS OR OTHER
	devices in energizing circuit	102	PREDETERMINED SCHEDULE MEANS
133	By impedance devices in	163	
133	energizing circuit		.Motor running-speed control
134	By circuit making and/or	164	Cyclically varying or repeated
134			speed schedules
125	braking devices	700	SYNCHRONOUS MOTOR SYSTEMS
135	LINEAR-MOVEMENT MOTORS	701	.Hysteresis or reluctance motor
136	AUXILIARY MEANS FOR PRODUCING		systems
	MECHANICAL STARTING OR	702	.Antihunting or damping
	ACCELERATING TORQUE	703	.Braking
137	.By auxiliary motor	704	.Pole changing motor winding
138	SPACE-DISCHARGE-DEVICE COMMUTATED		circuits
	MOTOR	705	.Synchronization systems
139	BATTERY-FED MOTOR SYSTEMS		
140	GENERATOR-FED MOTOR SYSTEMS	706	With armature power removal
140	HAVING GENERATOR CONTROL		upon failure to synchronize or
141			loss of synchronism
141	.Automatic generator control and/	707	Upon failure to resynchronize
	or with time-delay means	708	Responsive to thermal
142	Responsive to diverse		electrical element in system
	conditions or with time-delay	709	Having different armature
	means		voltage prior to synchronism
143	Plural electrical conditions	710	With d.c. field removal
144	Armature or primary current of	711	With electronic control
	motor	/ 1 1	
145	Terminal voltage or counter	710	element in system
113	e.m.f. of motor	712	With field excitation
146	Speed of motor or driven device		application
	_	713	Responsive to slip voltage
147	Speed or frequency of generator		frequency in d.c. field
	or its drive means		winding
1 / 0			
148	.Alternating-current-motor system	714	Responsive to armature current
148	.Alternating-current-motor system		Responsive to armature current
148	.Alternating-current-motor system	714 715	

716	.Field winding circuits	751	Split phase motor with
717	Responsive to a motor condition		capacitor interchangeably
718	Induced voltage in field		connected in series with
	winding		either primary winding
719	Speed responsive field power	752	With controlled electronic
	sources		device to provide the series
720	.Armature winding circuits		connection
721	Responsive to rotor shaft	753	With de-energizable start
	position or speed		winding
722	Having electronic power	754	With separate winding or
	conversion circuit		winding portion energized for
723	Having variable frequency		each direction of rotation
, 20	supply	755	Automatic current reversal on
724	Having a plurality of windings		start winding
724	or winding portions	756	With controlled electronic
725	REPULSION MOTOR SYSTEMS		switch for phase reversal
726	.With added motor winding or	757	.Braking
720	convertible to series motor	758	With diverse operation
727		759	Dynamic braking
	INDUCTION MOTOR SYSTEMS	760	Direct current primary winding
728	Repulsion start	700	braking circuit
729	.Power-factor control	761	Rotating rotor controls
730	.With plural separately movable	701	braking current in primary
	rotors		winding
731	.With voltage source connected to	762	With a.c. to d.c. conversion
	motor secondary	702	circuit
732	Electronic device controls	7.63	
	current in secondary circuit	763	Reversal of power to primary
733	Commutator connected to	7.64	winding
	secondary winding	764	Three phase power reversal
734	Slip rings connected to	765	Eddy current braking circuits
	secondary winding	766	.Primary and secondary circuits
735	Rotor shaft coupled to	767	.Primary circuit control
	dynamoelectric machine	768	Three phase motor operated from
736	Slip rings connected to		single phase source
	dynamoelectric machine winding	769	With dynamoelectric converter
737	.Self-cascaded motor windings	770	Dual voltage motors
738	.With commutated winding	771	Delta-wye, plural wye, or
739	.Reversing		plural delta connected primary
740	With diverse motor operation		windings
741	With braking	772	Plural speed
742	Electromagnetic brakes	773	Pole changing
743	Generator action	774	Single phase motor
744	Plugging	775	Separate primary running
745	With controlled saturable		winding for each pole number,
7 4 3	reactor in primary circuit		alternately energized
746	Two phase motor	776	Entire primary running
740	Two phase motor		winding energized for each
			running speed
748	With plural primary windings	777	Separate primary running
	or winding portions having		winding for each pole number,
740	common connection		alternately energized
749	Operating from a single phase	778	Starting control
750	source	779	With speed control
750	Shaded pole motor		

780	Three phase motor with	809	With voltage phase angle
	variable transformer to		control
	initially adjust voltage to	810	With voltage pulse time
	motor windings		control
781	Operating from a single phase	811	Pluse width modulation or
	source		chopping
782	With protective features	812	Voltage control
783	Thermal starting and thermal	813	With transformer
	overload protection	814	With impedance control
784	Impedance for reducing	815	Saturable reactor
	current during starting	816	Single phase, split phase
	operation	010	motors
785	Start winding removed during	817	With capacitor
	running operation	818	.Secondary circuit control
786	By electronic switch	819	
787	With transformer for	019	Open secondary member or
707	sensing the run winding		portion thereof with means to open or close the circuit
	current		-
788	With variable temperature	820	thereto
700	coefficient resistor in switch	820	Closed secondary member or
	control circuit		member portion with means to
789	By electromagnetic switch		change electrical
790	With relay coil in series	0.0.1	characteristics thereof
790		821	Impedance control of secondary
7.01	with main winding	000	circuit
791	By thermal switch	822	Responsive to motor condition
792	With variable temperature	823	Rotor speed or position
	coefficient impedance element		responsive
793	By centrifugal switch	824	Centrifugal force of rotor
		02.2	
794	Capacitor run motor with	021	controls secondary circuit
794	different capacitance at		controls secondary circuit impedance
	different capacitance at starting	825	controls secondary circuit
795	<pre>different capacitance at startingWith plural capacitors</pre>		controls secondary circuit impedance
	different capacitance at starting	825	<pre>controls secondary circuit impedanceInduction motor current</pre>
795	different capacitance at startingWith plural capacitorsSaturable winding in capacitor run motor circuit	825 826	<pre>controls secondary circuit impedanceInduction motor currentPrimary motor current</pre>
795	<pre>different capacitance at startingWith plural capacitorsSaturable winding in</pre>	825 826	controls secondary circuit impedanceInduction motor currentPrimary motor currentFrequency of secondary
795 796	different capacitance at startingWith plural capacitorsSaturable winding in capacitor run motor circuit	825 826 827	controls secondary circuit impedanceInduction motor currentPrimary motor currentFrequency of secondary current
795 796	different capacitance at startingWith plural capacitorsSaturable winding in capacitor run motor circuitPhase splitting using stator	825 826 827 828	controls secondary circuit impedanceInduction motor currentPrimary motor currentFrequency of secondary currentSecondary voltage
795 796	different capacitance at startingWith plural capacitorsSaturable winding in capacitor run motor circuitPhase splitting using stator winding mutual inductance or	825 826 827 828 829	controls secondary circuit impedanceInduction motor currentPrimary motor currentFrequency of secondary currentSecondary voltageBy manual operation
795 796 797	different capacitance at startingWith plural capacitorsSaturable winding in capacitor run motor circuitPhase splitting using stator winding mutual inductance or saturable winding	825 826 827 828 829	controls secondary circuit impedanceInduction motor currentPrimary motor currentFrequency of secondary currentSecondary voltageBy manual operation .With relatively movable cooperating motor parts to
795 796 797 798	different capacitance at startingWith plural capacitorsSaturable winding in capacitor run motor circuitPhase splitting using stator winding mutual inductance or saturable windingResponsive to motor condition	825 826 827 828 829	controls secondary circuit impedanceInduction motor currentPrimary motor currentFrequency of secondary currentSecondary voltageBy manual operation .With relatively movable
795 796 797 798	different capacitance at startingWith plural capacitorsSaturable winding in capacitor run motor circuitPhase splitting using stator winding mutual inductance or saturable windingResponsive to motor conditionResponsive to speed or	825 826 827 828 829 830	controls secondary circuit impedanceInduction motor currentPrimary motor currentFrequency of secondary currentSecondary voltageBy manual operation .With relatively movable cooperating motor parts to control energized motorAxially movable cooperating
795 796 797 798 799	different capacitance at startingWith plural capacitorsSaturable winding in capacitor run motor circuitPhase splitting using stator winding mutual inductance or saturable windingResponsive to motor conditionResponsive to speed or rotation phase angle	825 826 827 828 829 830	controls secondary circuit impedanceInduction motor currentPrimary motor currentFrequency of secondary currentSecondary voltageBy manual operation .With relatively movable cooperating motor parts to control energized motorAxially movable cooperating parts
795 796 797 798 799	different capacitance at startingWith plural capacitorsSaturable winding in capacitor run motor circuitPhase splitting using stator winding mutual inductance or saturable windingResponsive to motor conditionResponsive to speed or rotation phase angleWith controlled power conversion	825 826 827 828 829 830	controls secondary circuit impedanceInduction motor currentPrimary motor currentFrequency of secondary currentSecondary voltageBy manual operation .With relatively movable cooperating motor parts to control energized motorAxially movable cooperating partsDual stators, one or both
795 796 797 798 799 800 801	different capacitance at startingWith plural capacitorsSaturable winding in capacitor run motor circuitPhase splitting using stator winding mutual inductance or saturable windingResponsive to motor conditionResponsive to speed or rotation phase angleWith controlled power conversionIncluding inverter	825 826 827 828 829 830	controls secondary circuit impedanceInduction motor currentPrimary motor currentFrequency of secondary currentSecondary voltageBy manual operation .With relatively movable cooperating motor parts to control energized motorAxially movable cooperating partsDual stators, one or both angularly movable
795 796 797 798 799 800	different capacitance at startingWith plural capacitorsSaturable winding in capacitor run motor circuitPhase splitting using stator winding mutual inductance or saturable windingResponsive to motor conditionResponsive to speed or rotation phase angleWith controlled power conversion	825 826 827 828 829 830	controls secondary circuit impedanceInduction motor currentPrimary motor currentFrequency of secondary currentSecondary voltageBy manual operation .With relatively movable cooperating motor parts to control energized motorAxially movable cooperating partsDual stators, one or both angularly movable ALTERNATING CURRENT COMMUTATING
795 796 797 798 799 800 801 802	different capacitance at startingWith plural capacitorsSaturable winding in capacitor run motor circuitPhase splitting using stator winding mutual inductance or saturable windingResponsive to motor conditionResponsive to speed or rotation phase angleWith controlled power conversionIncluding inverterResponsive to an additional condition	825 826 827 828 829 830 831 832	controls secondary circuit impedanceInduction motor currentPrimary motor currentFrequency of secondary currentSecondary voltageBy manual operation .With relatively movable cooperating motor parts to control energized motorAxially movable cooperating partsDual stators, one or both angularly movable ALTERNATING CURRENT COMMUTATING MOTORS
795 796 797 798 799 800 801	different capacitance at startingWith plural capacitorsSaturable winding in capacitor run motor circuitPhase splitting using stator winding mutual inductance or saturable windingResponsive to motor conditionResponsive to speed or rotation phase angleWith controlled power conversionIncluding inverterResponsive to an additional conditionWith controlled a.c. to	825 826 827 828 829 830 831 832 244	controls secondary circuit impedanceInduction motor currentPrimary motor currentFrequency of secondary currentSecondary voltageBy manual operation .With relatively movable cooperating motor parts to control energized motorAxially movable cooperating partsDual stators, one or both angularly movable ALTERNATING CURRENT COMMUTATING MOTORS .Universal or A.CD.C. motors
795 796 797 798 799 800 801 802	different capacitance at startingWith plural capacitorsSaturable winding in capacitor run motor circuitPhase splitting using stator winding mutual inductance or saturable windingResponsive to motor conditionResponsive to speed or rotation phase angleWith controlled power conversionIncluding inverterResponsive to an additional conditionWith controlled a.c. to d.c. circuit in inverter	825 826 827 828 829 830 831 832 244 245 246	controls secondary circuit impedanceInduction motor currentPrimary motor currentFrequency of secondary currentSecondary voltageBy manual operation .With relatively movable cooperating motor parts to control energized motorAxially movable cooperating partsDual stators, one or both angularly movable ALTERNATING CURRENT COMMUTATING MOTORS .Universal or A.CD.C. motors SERIES MOTORS
795 796 797 798 799 800 801 802 803	different capacitance at startingWith plural capacitorsSaturable winding in capacitor run motor circuitPhase splitting using stator winding mutual inductance or saturable windingResponsive to motor conditionResponsive to speed or rotation phase angleWith controlled power conversionIncluding inverterResponsive to an additional conditionWith controlled a.c. to d.c. circuit in inverter supply	825 826 827 828 829 830 831 832 244	controls secondary circuit impedanceInduction motor currentPrimary motor currentFrequency of secondary currentSecondary voltageBy manual operation .With relatively movable cooperating motor parts to control energized motorAxially movable cooperating partsDual stators, one or both angularly movable ALTERNATING CURRENT COMMUTATING MOTORS .Universal or A.CD.C. motors SERIES MOTORS .Convertible for nonseries motor
795 796 797 798 799 800 801 802	different capacitance at startingWith plural capacitorsSaturable winding in capacitor run motor circuitPhase splitting using stator winding mutual inductance or saturable winding .Responsive to motor conditionResponsive to speed or rotation phase angleWith controlled power conversionIncluding inverterResponsive to an additional conditionWith controlled a.c. to d.c. circuit in inverter supplyWith controlled magnetic	825 826 827 828 829 830 831 832 244 245 246 247	controls secondary circuit impedanceInduction motor currentPrimary motor currentFrequency of secondary currentSecondary voltageBy manual operation .With relatively movable cooperating motor parts to control energized motorAxially movable cooperating partsDual stators, one or both angularly movable ALTERNATING CURRENT COMMUTATING MOTORS .Universal or A.CD.C. motors SERIES MOTORS .Convertible for nonseries motor operation
795 796 797 798 799 800 801 802 803	different capacitance at startingWith plural capacitorsSaturable winding in capacitor run motor circuitPhase splitting using stator winding mutual inductance or saturable winding .Responsive to motor conditionResponsive to speed or rotation phase angleWith controlled power conversionIncluding inverterResponsive to an additional conditionWith controlled a.c. to d.c. circuit in inverter supplyWith controlled magnetic reactance	825 826 827 828 829 830 831 832 244 245 246	controls secondary circuit impedanceInduction motor currentPrimary motor currentFrequency of secondary currentSecondary voltageBy manual operation .With relatively movable cooperating motor parts to control energized motorAxially movable cooperating partsDual stators, one or both angularly movable ALTERNATING CURRENT COMMUTATING MOTORS .Universal or A.CD.C. motors SERIES MOTORS .Convertible for nonseries motor operation .With plural, diverse or
795 796 797 798 799 800 801 802 803	different capacitance at startingWith plural capacitorsSaturable winding in capacitor run motor circuitPhase splitting using stator winding mutual inductance or saturable windingResponsive to motor conditionResponsive to speed or rotation phase angleWith controlled power conversionIncluding inverterResponsive to an additional conditionWith controlled a.c. to d.c. circuit in inverter supplyWith controlled magnetic reactanceResponsive to motor voltage	825 826 827 828 829 830 831 832 244 245 246 247	controls secondary circuit impedanceInduction motor currentPrimary motor currentFrequency of secondary currentSecondary voltageBy manual operation .With relatively movable cooperating motor parts to control energized motorAxially movable cooperating partsDual stators, one or both angularly movable ALTERNATING CURRENT COMMUTATING MOTORS .Universal or A.CD.C. motors SERIES MOTORS .Convertible for nonseries motor operation .With plural, diverse or diversely connected or
795 796 797 798 799 800 801 802 803 804 805 806	different capacitance at startingWith plural capacitorsSaturable winding in capacitor run motor circuitPhase splitting using stator winding mutual inductance or saturable windingResponsive to motor conditionResponsive to speed or rotation phase angleWith controlled power conversionIncluding inverterResponsive to an additional conditionWith controlled a.c. to d.c. circuit in inverter supplyWith controlled magnetic reactanceResponsive to motor voltageCondition responsive	825 826 827 828 829 830 831 832 244 245 246 247	controls secondary circuit impedanceInduction motor currentPrimary motor currentFrequency of secondary currentSecondary voltageBy manual operation .With relatively movable cooperating motor parts to control energized motorAxially movable cooperating partsDual stators, one or both angularly movable ALTERNATING CURRENT COMMUTATING MOTORS .Universal or A.CD.C. motors SERIES MOTORS .Convertible for nonseries motor operation .With plural, diverse or diversely connected or controlled sources of e.m.f.
795 796 797 798 799 800 801 802 803	different capacitance at startingWith plural capacitorsSaturable winding in capacitor run motor circuitPhase splitting using stator winding mutual inductance or saturable windingResponsive to motor conditionResponsive to speed or rotation phase angleWith controlled power conversionIncluding inverterResponsive to an additional conditionWith controlled a.c. to d.c. circuit in inverter supplyWith controlled magnetic reactanceResponsive to motor voltage	825 826 827 828 829 830 831 832 244 245 246 247	controls secondary circuit impedanceInduction motor currentPrimary motor currentFrequency of secondary currentSecondary voltageBy manual operation .With relatively movable cooperating motor parts to control energized motorAxially movable cooperating partsDual stators, one or both angularly movable ALTERNATING CURRENT COMMUTATING MOTORS .Universal or A.CD.C. motors SERIES MOTORS .Convertible for nonseries motor operation .With plural, diverse or diversely connected or

250	Impedance in series with field windings and in parallel to armature winding	284	With means to delay reversing until motor substantially stops
251	Field circuit control	285	Instant of, or passage or
252	Plural, diverse or diversely connected or controlled field	203	predetermined time or having time-delay means
	coils	286	Movement or position of motor
253	HOMOPOLAR OR UNIFORM FIELD MOTORS		or driven device
254	SELF-COMMUTATED IMPULSE OR	287	.Armature or primary circuit
	RELUCTANCE MOTORS		control
255	PLURAL DIVERSE MOTOR CONTROLS	288	Plural, diverse or diversely
256	.Motor-reversing		controlled armature windings
257	With running-speed control	289	Phase-reversal
258	And braking	290	Selectively energized windings
259	And acceleration control	291	Armature or primary current
260	And acceleration control		reversal
261	With braking	292	By shifting motor brushes or
262	And acceleration control		selecting appropriate set of
263	With acceleration control		brushes
264	With automatic starting and/or	293	Reversing polarity of current
201	stopping		supplied to armature circuit
265	Stopping upon predetermined	294	Wheatstone bridge type
200	movement of or position of	295	Potentiometer-controlled
	motor or driven device	296	.Field circuit control
266	At limit-of-travel of motor	297	Plural, diverse or diversely
200	or driven device		controlled field windings
267	Dual control circuits	298	Simultaneous energization
20,	alternately energized	299	With means for short-
268	.Running-speed control		circuiting a winding
269	With braking	300	Field-circuit current reversed
270	And acceleration control		
271	With acceleration control	Class 3	88 subclasses 800-841 are an inte-
272	With automatic starting and/or	gral pa	rt of this Class (Class 318), as
2,2	stopping		y the position of this box, and the schedule hierarchy of this
273	.Motor braking		retaining all pertinent definitions
274	With acceleration control		ss lines of this class.
275	With automatic starting and/or stopping	ana cra	os lines of this class.
276	.Acceleration control		
277	With automatic starting and/or	362	DDA WING
	stopping		BRAKING
278	In response to an electrical condition	363	."Spotting" or adjustment of braking controller during
279	Automatic stopping means less responsive during acceleration	364	coasting .Automatic and/or with time-delay
280	MOTOR-REVERSING		means
281	.Periodic- or intermittent- reversing	365	Plural diverse conditions or with time delay
282	In response to movement or	366	Condition of motor or driven device
	<pre>position (e.g., limit of travel) of motor or driven</pre>	367	Armature or primary current
	device	368	Armature or primary circuit
283	.Automatic and/or with time-delay		voltage or terminal or counter
203	means		e.m.f. voltage

369	Speed, acceleration, movement	438	POWER FACTOR CONTROL OF ARMATURE
	or position of motor or driven		OR LINE CIRCUIT
	device	439	MOTOR COMMUTATION CONTROL SYSTEMS
370	.Plural, diverse or diversely	440	HAVING PLURAL, DIVERSE OR
	controlled braking means		DIVERSELY CONTROLLED SOURCES
371	Including both friction braking	441	.A.C. and D.C.
	"plugging" and/or dynamic	442	.Different voltages
	braking	443	PERIODIC, REPETITIOUS OR
372	.Friction braking		SUCCESSIVE OPERATIONS CONTROL
373	."Plugging" or application of		OF MOTOR, INCLUDING "JOG" AND
	reverse power to motor		"INCH" CONTROL
374	Energy flow interrupted when	444	.Variable periods or intervals
	motor stops		between controlling operations
375	.Dynamic braking	445	AUTOMATIC AND/OR WITH TIME-DELAY
376	Regenerative		MEANS (E.G., AUTOMATIC
377	With additional source of		STARTING AND/OR STOPPING)
	e.m.f.	446	.With nonautomatic control means
378	In series with armature or		(e.g., manual)
	primary circuit	447	.Nonresponsive or less responsive
379	Locally closed armature circuit		for limited periods
380	Closed through impedance or	448	.Anti-hunting
	the like	449	.With respect to a fixed
381	With field or secondary		standard, master or reference
301	circuit control		device
382	.By auxiliary electric generator	450	Electrical detector
302	or by magnetic attraction or	451	Mechanically vibrating device
	repulsion devices	4 3 1	as reference device (e.g.,
383	"ANTI-BRAKING" OR BRAKING-		tuning fork)
303	PREVENTION MEANS	452	.Plural, diverse conditions or
	FREVENTION MEANS	452	with time-delay means
Class 38	8 subclasses 842-860 are an inte-	453	Electrical condition
gral par	t of this Class (Class 318), as	454	Plural, diverse electrical
-11	the position of this box, and	474	ridiai, diverse electricai
snown by	the position of this box, and		aonditions
_	the schedule hierarchy of this	155	conditions
follows	-	455	Voltage and current (e.g.,
follows Class, r	the schedule hierarchy of this		Voltage and current (e.g., watts)
follows Class, r	the schedule hierarchy of this etaining all pertinent definitions	456	Voltage and current (e.g., watts) .Rate-of-change of a condition
follows Class, r	the schedule hierarchy of this etaining all pertinent definitions	456 457	<pre>Voltage and current (e.g., watts) .Rate-of-change of a conditionInteria-type detector</pre>
follows Class, r	the schedule hierarchy of this etaining all pertinent definitions	456 457 458	Voltage and current (e.g., watts).Rate-of-change of a condition.Interia-type detector.Electrical condition
follows Class, r	the schedule hierarchy of this etaining all pertinent definitions is lines of this class. MOTOR LOAD, ARMATURE CURRENT OR	456 457	Voltage and current (e.g., watts) .Rate-of-change of a condition .Interia-type detector .Electrical condition .Terminal voltage or counter-electromotive force of
follows Class, r and Clas	the schedule hierarchy of this etaining all pertinent definitions is lines of this class. MOTOR LOAD, ARMATURE CURRENT OR FORCE CONTROL DURING STARTING	456 457 458 459	Voltage and current (e.g., watts) .Rate-of-change of a conditionInteria-type detectorElectrical condition .Terminal voltage or counter- electromotive force of controlled motor
follows Class, r and Clas	the schedule hierarchy of this etaining all pertinent definitions s lines of this class. MOTOR LOAD, ARMATURE CURRENT OR FORCE CONTROL DURING STARTING AND/OR STOPPING	456 457 458	Voltage and current (e.g., watts) .Rate-of-change of a condition .Interia-type detector .Electrical condition .Terminal voltage or counter-electromotive force of controlled motor .Sound, supersonic vibration or
follows Class, r and Clas	the schedule hierarchy of this etaining all pertinent definitions s lines of this class. MOTOR LOAD, ARMATURE CURRENT OR FORCE CONTROL DURING STARTING AND/OR STOPPING .Initial, "cracking" or "starting	456 457 458 459	Voltage and current (e.g., watts) .Rate-of-change of a condition .Interia-type detector .Electrical condition .Terminal voltage or counter-electromotive force of controlled motor .Sound, supersonic vibration or mechanical vibration
follows Class, r and Class 430	the schedule hierarchy of this etaining all pertinent definitions s lines of this class. MOTOR LOAD, ARMATURE CURRENT OR FORCE CONTROL DURING STARTING AND/OR STOPPING .Initial, "cracking" or "starting from rest" torque control	456 457 458 459 460 461	Voltage and current (e.g., watts) .Rate-of-change of a condition .Interia-type detector .Electrical condition .Terminal voltage or counter-electromotive force of controlled motor .Sound, supersonic vibration or mechanical vibration .Speed or rate-of-movement
follows Class, r and Clas	the schedule hierarchy of this etaining all pertinent definitions s lines of this class. MOTOR LOAD, ARMATURE CURRENT OR FORCE CONTROL DURING STARTING AND/OR STOPPING .Initial, "cracking" or "starting from rest" torque control CONSTANT MOTOR CURRENT, LOAD AND/	456 457 458 459 460 461 462	Voltage and current (e.g., watts) .Rate-of-change of a condition .Interia-type detector .Electrical condition .Terminal voltage or counter-electromotive force of controlled motor .Sound, supersonic vibration or mechanical vibration
follows Class, r and Class 430 431 432	the schedule hierarchy of this etaining all pertinent definitions s lines of this class. MOTOR LOAD, ARMATURE CURRENT OR FORCE CONTROL DURING STARTING AND/OR STOPPING .Initial, "cracking" or "starting from rest" torque control CONSTANT MOTOR CURRENT, LOAD AND/ OR TORQUE CONTROL	456 457 458 459 460 461 462 463	Voltage and current (e.g., watts) .Rate-of-change of a condition .Interia-type detector .Electrical condition .Terminal voltage or counter-electromotive force of controlled motor .Sound, supersonic vibration or mechanical vibration .Speed or rate-of-movement
follows Class, r and Class 430	the schedule hierarchy of this etaining all pertinent definitions is lines of this class. MOTOR LOAD, ARMATURE CURRENT OR FORCE CONTROL DURING STARTING AND/OR STOPPING .Initial, "cracking" or "starting from rest" torque control CONSTANT MOTOR CURRENT, LOAD AND/ OR TORQUE CONTROL .Control of motor load or device	456 457 458 459 460 461 462	Voltage and current (e.g., watts) .Rate-of-change of a condition .Interia-type detector .Electrical condition .Terminal voltage or counter-electromotive force of controlled motor .Sound, supersonic vibration or mechanical vibration .Speed or rate-of-movementCentrifugal-type detector
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follows Class, r and Class 430 431 432	the schedule hierarchy of this etaining all pertinent definitions is lines of this class. MOTOR LOAD, ARMATURE CURRENT OR FORCE CONTROL DURING STARTING AND/OR STOPPING .Initial, "cracking" or "starting from rest" torque control CONSTANT MOTOR CURRENT, LOAD AND/ OR TORQUE CONTROL .Control of motor load or device driven LIMITATION OF MOTOR LOAD,	456 457 458 459 460 461 462 463 464	Voltage and current (e.g., watts) .Rate-of-change of a condition .Interia-type detector .Electrical condition .Terminal voltage or counter-electromotive force of controlled motor .Sound, supersonic vibration or mechanical vibration .Speed or rate-of-movementCentrifugal-type detectorTachometer-type detectorElectric generator tachometer
follows Class, r and Class 430 431 432 433	MOTOR LOAD, ARMATURE CURRENT OR FORCE CONTROL DURING STARTING AND/OR STOPPING .Initial, "cracking" or "starting from rest" torque control CONSTANT MOTOR CURRENT, LOAD AND/ OR TORQUE CONTROL .Control of motor load or device driven LIMITATION OF MOTOR LOAD, CURRENT, TORQUE OR FORCE	456 457 458 459 460 461 462 463 464	Voltage and current (e.g., watts) .Rate-of-change of a condition .Interia-type detector .Electrical condition .Terminal voltage or counter-electromotive force of controlled motor .Sound, supersonic vibration or mechanical vibration .Speed or rate-of-movementCentrifugal-type detectorTachometer-type detectorElectric generator tachometer .In excess of a predetermined
follows Class, r and Class 430 431 432 433	MOTOR LOAD, ARMATURE CURRENT OR FORCE CONTROL DURING STARTING AND/OR STOPPING .Initial, "cracking" or "starting from rest" torque control CONSTANT MOTOR CURRENT, LOAD AND/ OR TORQUE CONTROL .Control of motor load or device driven LIMITATION OF MOTOR LOAD, CURRENT, TORQUE OR FORCE (E.G., PREVENTING OVERLOAD)	456 457 458 459 460 461 462 463 464 465	Voltage and current (e.g., watts) .Rate-of-change of a conditionInteria-type detectorElectrical condition .Terminal voltage or counter-electromotive force of controlled motor .Sound, supersonic vibration or mechanical vibration .Speed or rate-of-movementCentrifugal-type detectorTachometer-type detectorElectric generator tachometerIn excess of a predetermined valve
follows Class, r and Class 430 431 432 433 434	MOTOR LOAD, ARMATURE CURRENT OR FORCE CONTROL DURING STARTING AND/OR STOPPING .Initial, "cracking" or "starting from rest" torque control CONSTANT MOTOR CURRENT, LOAD AND/ OR TORQUE CONTROL .Control of motor load or device driven LIMITATION OF MOTOR LOAD, CURRENT, TORQUE OR FORCE (E.G., PREVENTING OVERLOAD) NONRUNNING, ENERGIZED MOTOR	456 457 458 459 460 461 462 463 464 465	Voltage and current (e.g., watts) .Rate-of-change of a conditionInteria-type detectorElectrical condition .Terminal voltage or counter-electromotive force of controlled motor .Sound, supersonic vibration or mechanical vibration .Speed or rate-of-movementCentrifugal-type detectorTachometer-type detectorElectric generator tachometerIn excess of a predetermined valve .Movement, position, or limit-of-
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follows Class, r and Class 430 431 432 433 434	MOTOR LOAD, ARMATURE CURRENT OR FORCE CONTROL DURING STARTING AND/OR STOPPING .Initial, "cracking" or "starting from rest" torque control CONSTANT MOTOR CURRENT, LOAD AND/ OR TORQUE CONTROL .Control of motor load or device driven LIMITATION OF MOTOR LOAD, CURRENT, TORQUE OR FORCE (E.G., PREVENTING OVERLOAD) NONRUNNING, ENERGIZED MOTOR	456 457 458 459 460 461 462 463 464 465	Voltage and current (e.g., watts) .Rate-of-change of a conditionInteria-type detectorElectrical condition .Terminal voltage or counter-electromotive force of controlled motor .Sound, supersonic vibration or mechanical vibration .Speed or rate-of-movementCentrifugal-type detectorTachometer-type detectorElectric generator tachometerIn excess of a predetermined valve .Movement, position, or limit-of-travelPlural sensing means for
follows Class, r and Class 430 431 432 433 434	the schedule hierarchy of this etaining all pertinent definitions s lines of this class. MOTOR LOAD, ARMATURE CURRENT OR FORCE CONTROL DURING STARTING AND/OR STOPPING .Initial, "cracking" or "starting from rest" torque control CONSTANT MOTOR CURRENT, LOAD AND/ OR TORQUE CONTROL .Control of motor load or device driven LIMITATION OF MOTOR LOAD, CURRENT, TORQUE OR FORCE (E.G., PREVENTING OVERLOAD) NONRUNNING, ENERGIZED MOTOR PHASING OR ANGULAR OR LINEAR	456 457 458 459 460 461 462 463 464 465	Voltage and current (e.g., watts) .Rate-of-change of a condition .Interia-type detector .Electrical condition .Terminal voltage or counter-electromotive force of controlled motor .Sound, supersonic vibration or mechanical vibration .Speed or rate-of-movement .Centrifugal-type detector .Tachometer-type detectorElectric generator tachometer .In excess of a predetermined valve .Movement, position, or limit-of-travel .Plural sensing means for determining plural positions

469	Overloading limit-of-travel-	500	.Plural sources of voltage
470	type control meansMagnitude of movement or		<pre>(including counter e.m.f. cells)</pre>
470	revolutions	501	.By shunting armature or primary
471	.Responsive to thermal conditions		winding
472	Of motor control means	502	.Variable length or tapped
473	In or about the motor being		armature winding
	controlled	503	.Frequency or pulsation control
474	.Motor load, armature or primary	504	.Voltage control
	or secondary circuit current	505	.By means to space-discharge
475	Mechanical-type detector (e.g.,		devices
	by yielding spring devices)	506	Plural, diverse or diversely
476	In excess of a predetermined		connected or controlled space-
	magnitude		discharge devices
477	Intentionally increased load	507	Having discharge-control means
478	.Electrical conditions in circuit		(e.g., grids)
	other than controlled motor	508	.Impedance-controlled
	circuit	509	Plural, diverse or diversely
479	Voltage		controlled impedances
480	.Radiant energy	510	Including both reactor and
481	.Pressure in a fluid or granular		condenser
	material	511	Inherently or self-variable
482	.Level of fluid or granular		impedance
	material	512	Inductive reactor controlled
483	.Moisture content or wetness	513	Having auxiliary means for
484	.Time or with time-delay means	E 1 4	saturating reactor core
485	Dash-pot or other mechanical	514	Resistor-controlled
106	delay means	515	Having short-circuiting means
486	Pilot- or servo-motors	516	Short-circuited step-by-step
487	Electromagnetic or inductive	519	.By armature or primary circuit-
400	time-delay means	520	making and/or breaking
488	Responsive to stress in body or material	520	Electromagnetically actuated FIELD OR SECONDARY CIRCUIT
489	Responsive to direction,	JZI	CONTROL
403	inclination or angular	523	.Plural, diverse or diversely
	position of bodies	223	connected or controlled field
490	WITH SIGNALS, METERS, RECORDERS		windings
150	OR TESTING DEVICES	524	Convertible number-of-poles
491	CONTROL OF BOTH MOTOR CIRCUIT AND		type (e.g., 4-pole or 6-pole)
	MOTOR STRUCTURE	525	Differentially wound or
492	MOTOR MAGNETIC ENERGY DISSIPATION		energized windings
493	CONTROL OF BOTH ARMATURE (OR	526	Series-parallel
	PRIMARY) CIRCUIT AND FIELD (OR	527	Series field winding
	SECONDARY) CIRCUIT	528	With means to short circuit a
494	ARMATURE (OR PRIMARY) CIRCUIT		field winding
	CONTROL	529	Selectively energized
495	.Plural, diverse or diversely	530	.Plural, diverse or diversely
	controlled, armature or		connected or controlled
	primary windings		sources of field circuit
496	Polyphase windings	E 0 4	voltage
497	Series-parallel	531	.Variable length or tapped field
498	Energized or controlled in	F20	winding
400	predetermined sequence	532	.By means of space-discharge
499	Wound or energized in magnetic	E22	device in field circuit
	opposition	533	.Impedance-controlled

534	Plural, diverse or diversely connected or controlled field
	circuit impedances
535	_
536	Wheatstone bridge
536	.By field circuit making and/or breaking
537	Intermittently operated
538	MOTOR STRUCTURE ADJUSTMENT OR
	CONTROL
539	.Both armature and field
	structures rotatable or
	adjustable
540	.Rotor element movable axially
541	.Brush or other current-collector
	control
542	Having movement toward or from
	cooperating part (e.g., brush
	lifted from commutator)
543	THREE-OR-MORE-POSITIONS MOTOR
	CONTROLLER SYSTEMS
544	.With other motor control device
545	Main line switch
546	.Plural, diverse or diversely
	controlled controllers
547	Plural control stations
548	.Plural control stations
549	.Return to "off", "starting" or
	"neutral" positions
550	Power-operated controllers
551	.Knee- or foot-operated
	controllers
552	.Power-actuated controllers
553	Separately actuated controller
	contacts
554	Electromagnetic actuated
555	Electromagnetic actuated
556	Reciprocating or oscillating
	electromagnetic means
557	Intermittent or step-by-step
	operation
558	MISCELLANEOUS

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FOR 000 CLASS-RELATED FOREIGN DOCUMENTS

DIGESTS

DIG 2 WINDSHIELD WIPER CONTROLS